The Limitations due to Exposure Detection Limits for Regression Models

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Biomarker use in exposure assessment is increasingly common, and consideration of related issues is of growing importance. Exposure quantification may be compromised when measurement is subject to a lower threshold. Statistical modeling of such data requires a decision regarding the handling of such readings. Various authors have considered this problem. In the context of linear regression analysis, Richardson and Ciampi (Am J Epidemiol 2003;157:355–63) proposed replacement of data below a threshold by a constant equal to the expectation for such data to yield unbiased estimates. Use of such an imputation has some limitations; distributional assumptions are required, and bias reduction in estimation of regression parameters is asymptotic, thereby presenting concerns about small studies. In this paper, the authors propose distribution-free methods for managing values below detection limits and evaluate the biases that may result when exposure measurement is constrained by a lower threshold. The authors utilize an analytical approach and a simulation study to assess the effects of the proposed replacement method on estimates. These results may inform decisions regarding analytical plans for future studies and provide a possible explanation for some amount of the discordance seen in extant literature.

bias (epidemiology); censored data; epidemiology, molecular; limit of detection; regression analysis

Abbreviations: \( dl \), detection limit; ND, “nondetects.”

The growing use of biomarkers in exposure assessment suggests the need to address issues related to their measurement. Even when levels are sufficient for measurement, some random exposure measurement error is expected, in part related to instrument precision. However, in many cases a proportion of study participants have levels at or below some experimentally determined detection limit (\( dl \)). Investigators are often interested in the risk of negative health outcomes associated with such levels. For example, studies of serum organochlorine levels, lipophilic xenobiotics, and breast cancer have determined that up to 99 percent of study participants have levels below the \( dl \) for some toxicants under study (1).

Biomarker quantification may be compromised if instrumentation cannot detect low levels. This may occur, for example, in quantitation of immunoassays (e.g., enzyme-linked immunosorbent assays) that require antigen concentrations sufficient for binding by antibodies. Highly specific binding conditions may impair antibody sensitivity and thereby challenge quantitation of low levels (2). Alternatively, assays may detect low biomarker levels but suffer from insufficient specificity, and measurement of exposure is hampered by background. The detection limit is often determined as a function of observed variance for a series of blanks; the terms “limit of detection” and “limit of quantification” generally correspond to three and 10, respectively, standard deviations from serial measurement of blanks (3). As such, numerical data are observable above and below the \( dl \); even among values above the threshold, it may not be possible to clearly delineate between those that...
are “real” and those that are not. Data below the threshold are often reported by laboratories as “nondetects,” and the data analyst or epidemiologist is limited to this qualitative assessment.

Statistical modeling of these data requires decisions regarding their handling (4, 5). Conventional approaches include omission, resulting in a truncated data set, and imputation with a constant, such as the \( dl \) or a fraction thereof (e.g., \( dl/2, dl/\sqrt{2} \)); or the observed values may be used directly or indirectly (4–7). Many of these imputations have their origins in well-behaved distributions, such as normal (in the case of \( dl/2 \)) and lognormal (in the case of \( dl/\sqrt{2} \)), and will yield correct inferences if these distributional assumptions are not grossly violated. Lubin et al. (5) propose a multiple imputation approach to handling nondetects when the exposure distribution can be assumed. Richardson and Ciampi (7) developed a coefficient of bias estimation of other regression parameters if the intercept is not equal to zero), investigators may exclude an intercept term if the intercept is known, such as reliability studies (when it is approximately zero) and unbounded (where values above the limit will be a mix of noise alone and signal) were considered. Additionally, the circumstances of instrument noise bounded by the detection limit (where the probability of values above the limit being due to error alone is approximately zero) and unbounded (where values above the limit will be a mix of noise alone and signal) were considered. We apply the contexts of linear regression models with both known and unknown intercepts and, additionally, provide an extension for application to logistic regression models.

**STATEMENT OF THE PROBLEM AND ANALYTICAL SOLUTION**

Let the observed continuous outcome, \( Y_i \), satisfy the following linear regression model:

\[
Y_i = \alpha + \beta x_i + e_i,
\]

with exposure variable \( x_i \), random noise \( e_i \), and regression parameters \( \alpha \) and \( \beta \). However, \( x \) is not observed. A lower threshold, \( dl \), interferes with measurement of low exposure levels. In a simple case, we observe \( z \), which equals either \( x \) or “nondetects” (ND), according to the following:

- For all \( x > dl \), \( z = x \)
- For all \( x \leq dl \), \( z = \text{ND} \).

Alternately, when the explanatory variable is less than \( dl \), there is quantitative random noise, \( \xi \), rather than the qualitative response, “ND.”

In this setting, the observations are \( \{Y_1, \ldots, Y_n, z_1, \ldots, z_n\} \). Without loss of generality, \( Y_i \) and \( z_i \) can be assumed to be scalars. This model can be considered in a more general context, where the exposure is measured with error, \( \eta \). Thus, the linear regression model is

\[
Y_i = \alpha + \beta z_i + e_i,
\]

and

\[
z_i = (x_i + \eta_i) I\{x_i + \eta_i \geq dl\} + \xi_i I\{x_i + \eta_i < dl\},
\]

\( i = 1, \ldots, n \)

is the exposure with measurement error, \( I\{\bullet\} \) is an indicator function (1 if \( \{\bullet\} \) is true and 0 otherwise), and \( e_i, \eta_i, \) and \( \xi_i \) are independent random disturbance terms related to regression error, measurement error, and detection limit error with \( f_\xi(u), f_\eta(u), \) and \( f_\xi(u) \) densities, respectively, and \( E(e_i) = 0, \text{var}(e_i) = \sigma_e^2 \).

The accuracy of regression parameter estimates depends upon the analytical approach to below-threshold values. One may consider substitution of observed \( z \) by \( z' \), whereby \( z'(a) = \begin{cases} x & \text{if } x \geq dl \\ a & \text{if } x < dl. \end{cases} \)

In this paper, least-squares estimation was used to determine an \( a \) that may be used in place of censored data for unbiased estimation of regression parameters. Nonnumerical and numerical instrument responses for below-threshold measurements were addressed. Additionally, the circumstances of instrument noise bounded by the detection limit (where the probability of values above the limit being due to error alone is approximately zero) and unbounded (where values above the limit will be a mix of noise alone and signal) were considered. We apply the contexts of linear regression models with both known and unknown intercepts and, additionally, provide an extension for application to logistic regression models.

**Nonnumerical indicator below the detection limit**

In certain situations, exposure variable values below \( dl \) are reported as “ND.” For example, this occurs when instrumentation is set to observe a threshold, and laboratory-supplied data sets include this notation for below-threshold observations. Such responses are clearly distinguished from numerical data; a decision regarding their management is required. Substitution of unobserved \( z_i \) is performed according to the following equation:

\[
z'_i = (x_i + \eta_i) I\{x_i + \eta_i \geq dl\} + a I\{x_i + \eta_i < dl\},
\]

\( i = 1, \ldots, n \).

**No intercept, \( \alpha \), models (condition 1A).** In cases where the intercept is known, such as reliability studies (when it is equal to zero), investigators may exclude an intercept term from models. This may also occur when modeling determinants of change from baseline or when centering data (8, 9). Even when the intercept of a general model is unknown, transformations are available to reduce its influence on estimation of other regression parameters if the intercept is not
of primary interest. In each of these circumstances, the intercept may be set to a constant, and the model becomes
\[ Y_i - \alpha = \beta z_i + \epsilon_i. \]
Without loss of generality, assume that the intercept equals zero.
Applying least-squares fitting to the unknown parameter \( \beta \) in the model depicted by equation 2 yields an estimator in the widely known form,
\[ \hat{\beta}_n = \frac{\sum_{i=1}^{n} Y_i z_i}{\sum_{i=1}^{n} (z_i)^2} = \beta + \hat{B}_n + E_n, \tag{4} \]
where
\[ \hat{B}_n = \frac{\sum_{i=1}^{n} (z_i - \bar{z})^2}{\sum_{i=1}^{n} (z_i)^2} \]
\[ = \frac{\sum_{i=1}^{n} (z_i - \bar{z})^2}{\sum_{i=1}^{n} (z_i)^2} \frac{\sum_{i=1}^{n} (-x_i \eta_i I\{x_i + \eta_i \geq dl\})}{\sum_{i=1}^{n} (z_i)^2} \]
\[ + \frac{a}{\sum_{i=1}^{n} (z_i)^2} \sum_{i=1}^{n} \eta_i I\{x_i + \eta_i \geq dl\} \]
\[ - \frac{\eta^2}{\sum_{i=1}^{n} (z_i)^2} I\{x_i + \eta_i \geq dl\} \] \tag{5}

signifies the bias to the regression parameter, and
\[ E_n = \frac{\sum_{i=1}^{n} e_i z_i}{\sum_{i=1}^{n} (z_i)^2} \]
signifies noise with expectation zero. Assume that exposure, \( x \), has some distribution, \( F_x \), and is independent of \( e \) and \( \eta \).
Therefore, directly from equation 5, with \( \eta_i = 0 \), there are two solutions that yield an unbiased estimator \( \hat{\beta}_n \) (i.e., \( \hat{B}_n = 0 \)): when \( a = a_1 \) or when \( a = a_2 \) (for details and solution without the restriction on \( \eta_i \), refer to appendix 1):
\[ a_1 = \frac{\sum_{i=1}^{n} x_i I\{x_i < dl\}}{\sum_{i=1}^{n} I\{x_i < dl\}} \tag{6a} \]
or
\[ a_2 = 0. \tag{6b} \]
Asymptotically (as \( n \to \infty \)), \( a_1 \) is approximately equal to \( E(x| x < dl) \) under the condition \( E(x^2) < \infty \). Replacement of values below the detection limit by this value was proposed by Richardson and Ciampi (7); however, as shown in equation 6b, the solution is not unique. There are important distinctions between these two methods; use of equation 6a assumes knowledge of the distribution function of \( x \), whereas for \( a = 0 \), no distributional assumptions are needed.
Additionally, there are differences regarding the variance of the bias resulting from detection limit error. The variance of bias, \( \text{var}(\hat{\beta}_n|x) \), under \( a_1 \) (equation 6a) is shown as
\[ \text{var}(\hat{\beta}_n|x; a_1) = \beta^2 o_1(1) \]
\[ + \frac{\sigma^2}{\sum_{i=1}^{n} (x_i - \bar{x})^2 I\{x_i \geq dl\} + (E(x|x < dl))^2 \sum_{i=1}^{n} I\{x_i < dl\}} \]
\[ \lim_{n \to \infty} \sup_{\beta} \text{var}(\hat{\beta}_n|x; a_1) = \infty \tag{7a} \]
with asymptotic properties represented by the function \( o_1(1) \), which approaches 0 as \( n \) goes to infinity. Estimates will have some amount of bias for a fixed sample size. Conversely, under the second solution, equation 6b, the variance is derived as
\[ \text{var}(\hat{\beta}_n|x; a_2) = \frac{\sigma^2}{\sum_{i=1}^{n} (x_i - \bar{x})^2 I\{x_i \geq dl\}} . \tag{7b} \]
Note that the variance solution using \( a_1 \) comprises two terms, the first being a proportion of the parameter of interest, dependent upon the sample size. The solution using \( a_2 \) is invariant of the unknown parameter \( \beta \); however, for “small” \( \beta \), the variance may exceed that when \( a_1 \) is used.

Models that estimate the intercept, \( \alpha \) (condition 1B). Commonly, investigators have no foreknowledge of the intercept value or a need to center their data, and the regression intercept must be estimated. As previously, consider the situation where nonnumerical noise is returned below \( dl \). As in the previous discussion, \( \eta \) can be assumed to be zero, and hence the imputation is \( z' = x I\{x \geq dl\} + a I\{x < dl\} \). Using least-squares estimation, the slope parameter estimator based on \( z' \) instead of \( x \) can be shown as
\[ \hat{\beta}_n = \frac{\sum_{i=1}^{n} (Y_i - \frac{1}{n} \sum_{j=1}^{n} Y_j) z'_i}{\sum_{i=1}^{n} (z'_i)^2} . \tag{8} \]
Again, bias results from using \( z' \) for estimation instead of the true explanatory variables (refer to appendix 2 for equations for bias). As previously, there are two solutions for \( a \) to yield the unbiased estimator shown in equation 8. The bias is zero if and only if
\[ a = \frac{\sum_{i=1}^{n} x_i I\{x_i < dl\}}{\sum_{i=1}^{n} I\{x_i < dl\}} . \tag{9a} \]
or
\[ a = \frac{\sum_{i=1}^{n} x_i I\{x_i \geq dl\}}{\sum_{i=1}^{n} I\{x_i \geq dl\}} . \tag{9b} \]
As in the previous circumstance, the Richardson and Ciampi solution (equation 9a) is valid here. Since \( x I\{x < dl\} \) is not observed, application of this solution requires that some distribution, \( F_x \), be assumed for determination of the mean of the missing values. Additionally, the asymptotic result, \( a \approx E(x| x < dl) \), as \( n \to \infty \) must be assumed to be valid. However, the second solution (equation 9b) requires neither distributional nor asymptotic assumptions: The replacement value \( a \) may be calculated.

Numerical noise below the limit of detection

Whereas the previous sections concerned the instrumentation response of “ND,” numerical information may be available for data below \( dl \). Importantly, if detection limit error is known to be less than the \( dl \) itself (\( \xi \) is reasonably
bounded by the \( dl \), observations below \( dl \) may be identified as such, and this becomes a special case of section 1. In this case, investigators may follow the previously discussed methodologies for models with or without intercept.

When \( \xi \) is unknown or is known to have greater magnitude than \( dl \), the observations due to noise cannot be easily identified; the \( \xi \) are observed both above and below \( dl \) for all individuals, and those with detection limit error are not easily discernible from those free of this error. Formally, suppose \( \Pr(\xi > dl) > 0 \). Under the described scenario of detection limit error, this may be the case if the detection limit is set as two, rather than three (limit of detection) or 10 (limit of quantification) standard deviations of noise. In this circumstance, there is no simple approach to determining an optimal imputation; however, numerical approaches for models both with and without intercept are shown in appendix 3.

Alternatively, detection limits are occasionally determined solely on the basis of the distribution of additive random error (or concurrent detection of some contaminant). Consider true exposure, \( x \), and all concurrently detected others, \( \omega \); all samples may be reasonably thought of as the sum of these two components (i.e., \( x + \omega \)). When all levels of \( x \) are subject to the same source of error, which is independent of \( x \), then the proposed imputations remain valid; however, alternatively, the observed values may be used for analysis in combination with commonly used methods for handling random measurement error (10, 11).

**Motivating Example**

We consider the association between total cholesterol and serum vitamin E in a healthy population using a population-based sample of randomly selected residents aged 35–79 years who lived in two counties in western New York State. After exclusions, a total of 857 men and women were selected for analysis. Blood specimens were analyzed for routine chemistry, hematology, and a number of chronic disease and nutritional factors, as well as serum vitamin E levels.

For cholesterol and vitamin E, all observations were measured above the \( dl \). Regression analysis suggests a linear association between serum cholesterol and serum vitamin E (\( \beta = 4.07, R^2 = 0.14, p < 0.0001 \)). However, if one stipulates that 30 percent of serum vitamin E levels are below the \( dl \), the question arises on how to treat these “unobserved” values.

To this end, estimates were compared from linear regression of serum cholesterol on serum vitamin E. For exposure data, these models used one of the four following options: 1) all available exposure data (“gold standard”); 2) replacement of all data below the imposed threshold with the mean level of vitamin E of all data below the threshold; 3) the mean of all data above the threshold; or 4) zero. Importantly, the second circumstance relies on distributional assumptions that would be unverifiable under a true detection limit. Models were run for the known intercept as well as for estimation of the intercept.

Table 1 displays results of the known intercept regression. Replacement of subthreshold data by the average of subthreshold data yielded estimates almost identical to those when all data were used. However, under usual conditions, direct calculation of this quantity is not possible, and it must be estimated assuming some distribution. Conversely, replacement by zero requires no such assumptions and resulted in estimates not statistically different from those under the ideal scenario of no threshold. Table 2 displays results of linear regression models estimating both slope and intercept. Use of the proposed average of above-threshold data for replacement of missing data yielded good estimates of parameters, both intercept and slope. As with the use of zero for no-intercept models, use of this imputation for estimation is nonparametric and requires no distributional

| TABLE 1. Coefficient estimates from linear regression with a known intercept of serum cholesterol on serum vitamin E, with values below the limit of detection replaced by the average \((x|x < dl^a)\) and zero |
|---|
| **All values (reference)** | **Replace by average \((x|x < dl)\)** | **Replace by zero** |
| \( \beta \) | 4.07 | 4.06 | 4.19 |
| SE* \((\hat{\beta})\) | 0.14 | 0.14 | 0.15 |
| 95% CI* \((\hat{\beta})\) | 3.80, 4.34 | 3.79, 4.33 | 3.90, 4.48 |

* \( dl \), detection limit; SE, standard error; CI, confidence interval.

| TABLE 2. Coefficient estimates from linear regression of serum cholesterol on serum vitamin E, with values below the limit of detection replaced by the average \((x|x < dl^a)\), average \((x|x > dl)\), and zero |
|---|
| **All values (reference)** | **Replace by average \((x|x < dl)\)** | **Replace by average \((x|x > dl)\)** | **Replace by zero** |
| \( \hat{\beta} \) | 196.88 | 197.39 | 204.53 | 219.76 |
| SE* \((\hat{\beta})\) | 5.21 | 5.26 | 7.51 | 3.35 |
| 95% CI* \((\hat{\beta})\) | 186.67, 207.09 | 187.08, 207.7 | 189.81, 219.25 | 213.19, 226.33 |
| \( \hat{\beta} \) | 4.07 | 4.03 | 3.02 | 2.89 |
| SE \((\hat{\beta})\) | 0.36 | 0.36 | 0.46 | 0.24 |
| 95% CI \((\hat{\beta})\) | 3.36, 4.78 | 3.32, 4.74 | 2.12, 3.92 | 2.42, 3.36 |

* \( dl \), detection limit; SE, standard error; CI, confidence interval.
knowledge. Moreover, estimates of slope were hampered by slight departures from the assumptions of linear regression of the data. Use of zero for replacement of missing data resulted in estimates statistically different from those under no constraint by a detection threshold.

LOGISTIC REGRESSION

Frequently, investigators face exposure measurement thresholds when investigating binary outcomes (e.g., presence or absence of disease) using logistic regression models for evaluation of risk. These models are often used for analysis of case-control study data. In this context, investigators rarely have an interest in intercept estimates, interpretation of which is generally meaningless (9). In such situations, the discussion for condition 1A is applicable, and bias is minimized when \( a \) equals zero. This is shown empirically in a simulation study described in the next section. A more detailed discussion and proof are shown in appendices 4 and 5.

The solution under maximum likelihood estimation is complicated, even with known intercept. When the intercept is unknown, solutions to two nonlinear equations are required (appendix 5). A solution can be determined only in rare cases and where strong assumptions regarding the observed data are used and where the proposed methodology is applied. However, this problem is beyond the scope of this paper.

MONTE CARLO SIMULATION STUDY

We extend previous work (7) to apply a solution to the detection limit problem to binary disease variables and to use of a logit-linear model. To evaluate the effects of detection limit bias on logistic regression, 10,000 data sets were simulated, with \( n = 300 \), outcome \( Y \), and measured exposure \( z \) to comprise the observations \( \{(Y_i, z_i(a)), i = 1, \ldots, n\} \), following the model,

\[
P(Y_i = 1 | x_i) = (1 + \exp(-c - \beta x_i))^{-1},
\]

\[
z_i(a) = x_i I\{x_i \geq dl\} + a I\{x_i < dl\}.
\]

We evaluated two distributions for the exposure of interest. A bimodal distribution was chosen to exemplify a poorly behaved density, and a gamma distribution (a skewed distribution often assumed for biomarkers) was also evaluated (figure 1). After data for the true exposure were generated, several detection thresholds were applied. The observed exposure was determined after replacement of values below the detection limit for both \( a_1(a = E(x|x < dl)) \) and \( a_2(a = 0) \) according to the above, as well as for the common imputations \( a = dl \) and \( a = dl/2 \). Bias and variance were assessed by comparing results based on use of true exposure with those subject to detection limits.

Table 3 displays the simulated Monte Carlo variance of the maximum likelihood estimator \( \hat{\beta} \), \( \text{var}(a) = (\hat{\beta} - \beta)^2 \), and the Monte Carlo average bias, \( \text{bias}(a) = \hat{\beta} - \beta \), for each evaluated \( a \) under the bimodal distribution for exposure. The specified values for \( dl \) correspond to the circumstances where 25 percent, 50 percent, and 75 percent of data are below the threshold. In most cases, imputation of zero resulted in minimally biased estimates, with Monte Carlo relative biases comparable with those observed under use of the \( E(x|x < dl) \). Imputation of \( dl \) and \( dl/2 \) resulted in substantially greater biases. Table 4 displays the results of simulations where exposure is gamma distributed. Results for the gamma-distributed exposure were similar to those for the bimodal distribution; imputation of zero and \( E(x|x < dl) \) performed similarly well, while use of \( dl \) or \( dl/2 \) resulted in substantially biased estimates.
TABLE 4. Logistic regression simulation study with gamma distributed exposure: bias and variance of the estimator under replacement value, \( a \), equal to zero, \( E(x|x<dl^*) \), \( dl \), and \( dl/2 \)

<table>
<thead>
<tr>
<th>( \beta )</th>
<th>( dl )</th>
<th>( x &lt; dl ) (%)</th>
<th>Bias (Monte Carlo estimator of ( \beta ))</th>
<th>Variance (Monte Carlo estimator of ( \beta ))</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td></td>
<td>( a = 0 )</td>
<td>( a = 0 )</td>
</tr>
<tr>
<td>0.3</td>
<td>5</td>
<td>25</td>
<td>0.00026</td>
<td>0.00019</td>
</tr>
<tr>
<td></td>
<td>8.5</td>
<td>50</td>
<td>0.00068</td>
<td>0.00059</td>
</tr>
<tr>
<td></td>
<td>12</td>
<td>75</td>
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<td>-0.00796</td>
</tr>
<tr>
<td>0.5</td>
<td>5</td>
<td>25</td>
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</tr>
<tr>
<td></td>
<td>8.5</td>
<td>50</td>
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<td>-0.00518</td>
</tr>
<tr>
<td></td>
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<tr>
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<tr>
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<td>50</td>
<td>0.00668</td>
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</tr>
<tr>
<td></td>
<td>12</td>
<td>75</td>
<td>-0.12120</td>
<td>-0.07991</td>
</tr>
</tbody>
</table>

\( * dl \), detection limit.

\( \dagger \) Values of \( E(x|x<d) \) are as follows: 3.405 for \( d = 5 \); 4.934 for \( d = 8.5 \); 6.700 for \( d = 12 \). \( P(Y_i = 1|x_i) = (1 + \exp(-c - j|x_i))^{-1} \), where \( c = -5 \), \( c \) is known, and \( x_i \sim Gamma(shape = 4, scale = 4) \).
under the proposed imputations were not statistically different from those subjected to no detection threshold nor were they identical. In combination with normal sampling variability, when data do not perfectly conform to the assumptions for linear regression, this is expected to be the case. Nonlinear relations can be poorly represented when a subset of data is observable. Additionally, when error is not normally and/or identically distributed, data with disproportionate leverage on estimation may be subject to the threshold, and the parameter estimates may be unequal to those without a detection threshold. Importantly, in these cases, the estimates under a no-threshold linear model are subject to the same limitations; data transformation techniques should be considered. Under the assumptions of linear regression, imputation of zero for no intercept or of the mean of observed values for intercept models is appropriate for investigators opting for nonparametric approaches.

Various approaches to management of data measured with a lower limit including imputations derived from the limit of detection itself, such as $dl/2$ or $dl/\sqrt{2}$, have been used in laboratory and data analysis settings (4, 6, 12). A multiple imputation approach based on bootstrapping has also been proposed (5). The utility of these approaches depends upon proper determination of the exposure distribution. Recent work showed that use of $E(x|x < dl)$ for those data below detection limits allows unbiased estimation of linear and, under certain conditions, logistic regression parameters; however, this approach requires assumptions regarding the underlying exposure distribution. We have shown that unbiased estimates may also be obtained if data below the detection limit are replaced by zero for no-intercept models and by $E(x|x > dl)$ for models estimating the intercept; use of these methods requires no distributional assumptions.

We performed Monte Carlo simulations of bimodal and gamma exposures with a logit-linear relation to the outcome and stipulated varying proportions of the data to be below a detection threshold. Under a no-intercept model ($\alpha = 0$) with slope parameter equal to 0.3 (odds ratio = 1.35), imputation of zero resulted in similarly minimally biased results as use of $E(x|x < dl)$. This approach may be useful for logistic regression models when available information makes distributional assumptions difficult to validate, thereby extending upon previously published work (7). We have presented analytical solutions for linear regression and no-intercept logistic regression; the solutions presented here are not generalizable to other complex modeling situations.

CONCLUSION

Measurement of laboratory data can be limited by a detection threshold when sample exposure levels are in the range of that threshold. When a meaningful proportion of data falls below the detection threshold, there is a need for simple yet valid approaches to handling the data. When investigators are confident of the validity of distributional assumptions, parametric methods may be used. We have demonstrated approaches that require no distributional assumptions and are easily applied to achieve unbiased estimates. In all cases, sensitivity analyses to evaluate the chosen approach are recommended. Importantly, this paper has focused on analytical studies primarily interested in estimating linear relations between signal and response. Nevertheless, investigators should evaluate the nature of the data, the detection limit, and the parameter to be estimated when choosing the optimal method for management of subthreshold data.

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REFERENCES

APPENDIX 1

Application of the definition for \( z' \) from equation 3,
\[
z'_i = (x_i + \eta_i) I\{x_i + \eta_i \geq d\} + a I\{x_i + \eta_i < d\}, \quad i = 1, \ldots, n,
\]
to equation 5 for the least-squares estimator with detection limit error,
\[
\hat{B}_n = \beta \frac{\sum_{i=1}^{n} (x_i - z'_i) z'_i}{\sum_{i=1}^{n} (z'_i)^2},
\]
yields the following:
\[
\hat{B}_n = \beta \frac{\sum_{i=1}^{n} (x_i - z'_i) z'_i}{\sum_{i=1}^{n} (z'_i)^2}.
\]
The bias of estimator \( \hat{B}_n \) is zero (i.e., \( \hat{B}_n = 0 \)) if and only if the numerator of \( \hat{B}_n \) (equation 5) is equal to zero:
\[
a^2 \frac{\sum_{i=1}^{n} (x_i + \eta_i < d)}{\sum_{i=1}^{n} (z'_i)^2} - a \frac{1}{n} \sum_{i=1}^{n} x_i I\{x_i + \eta_i < d\} + \frac{1}{n} \sum_{i=1}^{n} (\eta_i^2 I\{x_i + \eta_i \geq d\} + x_i \eta_i I\{x_i + \eta_i \geq d\}) = 0. \quad (A1.1)
\]
Asymptotically (as \( n \to \infty \)), under the restrictions 1) \( E(x^2) < \infty \), 2) \( E(\eta^2) < \infty \), and 3) \( E(x \eta^2) < \infty \), the solution of equation 5 is almost surely equal to the solution of
\[
a^2 \Pr\{x_1 + \eta_1 < d\} - a E(x_1, x_1 + \eta_1 < d) + E(\eta_1^2, x_1 + \eta_1 \geq d) + E(x_1 \eta_1, x_1 + \eta_1 \geq d) = 0. \quad (A1.2)
\]
The preceding determines an “\( a \)” such that bias, \( \hat{B}_n \), equals zero, asymptotically. When detection limit error can be clearly delineated, that is, \( \Pr(\xi < d) = 1 \), \( a \) may be either \( a_1 = E(x|x < d) \) or \( a_2 = 0 \).

APPENDIX 2

For estimation of the regression parameter and unknown intercept when exposure is measured with a threshold,
\[
\hat{B}_n = \beta \frac{\sum_{i=1}^{n} z'_i (x_i - \frac{1}{n} \sum_{j=1}^{n} x_j) - \sum_{i=1}^{n} z'_i (\frac{1}{n} \sum_{j=1}^{n} z'_j)^2}{\sum_{i=1}^{n} (z'_i - \frac{1}{n} \sum_{j=1}^{n} z'_j)^2}.
\]
The numerator of \( \hat{B}_n \) may be demonstrated as
\[
\sum_{i=1}^{n} z'_i \left( x_i - \frac{1}{n} \sum_{j=1}^{n} x_j \right) - \sum_{i=1}^{n} z'_i \left( \frac{1}{n} \sum_{j=1}^{n} z'_j \right)^2
\]
\[
= \sum_{i=1}^{n} x_i I\{x_i \geq dl\} + \frac{a}{n} \sum_{i=1}^{n} x_i I\{x_i < dl\} - \frac{1}{n} \sum_{i=1}^{n} x_i \sum_{i=1}^{n} x_i I\{x_i \geq dl\} - \frac{a}{n} \sum_{i=1}^{n} x_i \sum_{i=1}^{n} I\{x_i < dl\} - \frac{a^2}{n} \sum_{i=1}^{n} I\{x_i \geq dl\} - \frac{a^2}{n} \sum_{i=1}^{n} I\{x_i < dl\} + \frac{2a}{n} \sum_{i=1}^{n} x_i I\{x_i \geq dl\} \sum_{i=1}^{n} I\{x_i < dl\} + \frac{a^2}{n} \left( \sum_{i=1}^{n} I\{x_i \geq dl\} \right)^2 \quad (A2.1)
\]
Hence, the bias is equal to zero if the right side of equation A2.1 is equal to zero.

APPENDIX 3

For models not estimating the intercept with a numerical response below \( dl \) rather than “ND,” first define a substitution of observed \( z \),
\[
z'_i(a) = z_i I\{z_i \geq dl'\} + a I\{z_i < dl'\}, \quad \text{for } i = 1, \ldots, n,
\]

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where \( dl' \) is the fixed detection limit. The bias of the least-squares estimator is given by

\[
\hat{B}_n = \beta \sum_{i=1}^{n} \frac{(x_i - z'_i)z'_i}{\sum_{i=1}^{n} (z'_i)^2}.
\] (A3.2)

In this case, bias \( \hat{B}_n \) is asymptotically close to zero if \( a \) and \( dl' \) are solutions of the equation,

\[
E(z'_i x_1) - E(z'_i)^2 = 0.
\] (A3.3)

Solving equation A3.3 requires that the distribution functions of \( x_i, \eta_i, \) and \( \xi \) be assumed, which may be performed numerically by grid searching \( a \) and \( dl' \) such that the left side of equation A3.3 is approximately equal to zero.

When the density function of regression error is known and well behaved, then we may consider maximum likelihood estimation of \( \beta \),

\[
\hat{\beta}_n = \arg \max_b \prod_{i=1}^{n} f_c(Y_i - bz'_i),
\] (A3.4)

and the consideration of bias reduction from conditions 1A and 1B is similarly relevant here.

To address a numerical response below \( dl \) when estimating the intercept, we use the replacement defined in appendix equation A3.1. Using the proposed method, in the case where the distributions of all random variables in equation 1 are known, we obtain the unbiased least-square estimator of parameter \( \beta \) based upon the sample \{\( Y, z' \)\} by applying \( a \) and \( dl' \) such that

\[
E[z' (x - E(x))] - E[z' - E(z')]^2 = 0.
\]

---

**APPENDIX 4**

Note that, asymptotically, by the definition of least-squares slope parameter estimators under the detection limit problem (e.g., equation A1.2), we attain \( E\hat{\beta}_n \to \lambda \beta \), where \( \lambda = \frac{\text{var}(x, z')}{\text{var}(z)} \). This form is similar to an asymptotic property of the ordinary least-squares estimator of the parameters from linear regression with additive measurement error (7).

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**APPENDIX 5**

The logistic regression model with exposure measurement error is given by

\[
P(Y_i = 1|x_i) = (1 + e^{-\beta z'_i})^{-1},
\]

\[
z'_i = (x_i + \eta_i) I\{x_i + \eta_i \geq d\} + \xi_i I\{x_i + \eta_i < d\}, \quad i = 1, \ldots, n,
\] (A5.1)

where \( Y_i, i = 1, \ldots, n \) are Bernoulli variates whose exact distribution depends on the predictor \( x_i \). Let \( x_i + \eta_i \) be observed if \( x_i + \eta_i \geq d \); hence, we assume a substitution of observed \( z_i \) by \( z'_i = (x_i + \eta_i) I\{x_i + \eta_i \geq d\} + a I\{x_i + \eta_i < d\}, \quad i = 1, \ldots, n. \)

Applying the maximum likelihood method, we obtain the estimator of \( \beta \) by solving the following:

\[
\sum_{i=1}^{n} z'_i \left( Y_i - \frac{e^{\hat{\beta}_n z'_i}}{1 + e^{\hat{\beta}_n z'_i}} \right) = 0.
\]

It follows from the usual Taylor expansion that

\[
\hat{\beta}_n - \beta = \left[ \sum_{i=1}^{n} z'_i \left( Y_i - \frac{e^{\beta z_i}}{1 + e^{\beta z_i}} \right) + \beta \sum_{i=1}^{n} z'_i(z_i - z'_i) Q_i \left[ \sum_{i=1}^{n} (z_i)^2 Q_i \right]^{-1} \right] Q_i \in \left( \frac{e^{\hat{\beta}_n z'_i}}{(1 + e^{\hat{\beta}_n z'_i})^2}, \frac{e^{\hat{\beta}_n z'_i}}{(1 + e^{\hat{\beta}_n z'_i})^2} \right).
\] (A5.2)
Thus, in this case, the detection limit error bias is defined by

\[
\hat{B}_n = \frac{\beta \sum_{i=1}^{n} z_i (x_i - z_i) Q_i}{\sum_{i=1}^{n} (z_i)^2 Q_i}.
\]  

(A.5.3)

Therefore, even though \( \eta_i = 0, i = 1, \ldots, n \), we obtain

\[
\hat{B}_n = \frac{\beta \sum_{i=1}^{n} (ax_i I(x_i < d) - a^2 I(x_i < d)) Q_i}{\sum_{i=1}^{n} (z_i)^2 Q_i},
\]

where \( \hat{B}_n \) is zero only if \( a \) is zero, because generally \( Q_i \) is dependent on \( i \), target unknown \( \beta \), and unobserved \( x_i \).