Implementation of insect pest management strategies depends on the ability to characterize the abundance and seasonality of populations. Consequently, monitoring efforts are of prime importance. In many insect species, traps baited with semiochemicals, such as synthetic pheromones, provide a reliable and cost-effective method of sampling (Silverstein 1981, Ridgway et al. 1990, Flint and Doane 1996). In the case of the gypsy moth, *Lymantria dispar* (L.), pheromone-baited traps are deployed under two USDA gypsy moth management programs. One program, Slow the Spread, aims to monitor the progression of the leading population edge as it continues to invade the United States (Tobin and Blackburn 2007), whereas the other, eradication programs, aims to detect newly arrived populations in areas far from its established distribution (USDA 2001, Hajek and Tobin 2009). Between these two management efforts, ≈250,000 traps are placed annually across the continental United States to detect incipient colonies of gypsy moth, some of which are targeted for management and to estimate population density. These traps are very effective at low population densities. The pheromone is also very specific and generally attracts only gypsy moth males and is stable over time so that it does not need to be replaced during the course of the flight season.

The gypsy moth is a univoltine defoliator that can feed on >300 species of deciduous and coniferous host trees, and preferred host species include oak, willow, and aspen (Elkinton and Liebhold 1990, Liebhold et al. 1995). In North America, females do not fly and oviposit in close proximity to the site of adult emergence (Odell and Mastro 1980). Dispersal is mostly accomplished through early instar ballooning, and the anthropogenic movement of life stages (Doane and McManus 1981, Elkinton and Liebhold 1990, Hajek and Tobin 2009). Unlike many sampling programs conducted in support of integrated pest management (IPM), the goal of gypsy moth trapping is to detect incipient populations and estimate population abundance (USDA 2001, Tobin and Blackburn 2007), as opposed to determining the appropriate timing of management decisions (Elkinton and Cardé 1981). However, the timing of trap deployments is a critical issue, especially because gypsy moth monitoring programs occur over a geographically large and climatically diverse area; thus, the appropriate time to
set and remove traps is considerably variable depending on the location being monitored. The Slow the Spread monitoring area extends from Minnesota to North Carolina, whereas eradication programs monitor for gypsy moth west and south of the Slow the Spread. Consequently, gypsy moth males can be generally active in flight from June (e.g., North Carolina) to September (e.g., northern Minnesota) depending on local climatic conditions.

Fortunately, gypsy moth monitoring programs have the luxury of several robust phenology models that can be used to predict the occurrence of lifecycle events (Johnson et al. 1983; Logan et al. 1991; Sheehan 1992; Gray et al. 1995, 2001; Régnière and Sharov 1998; Gray 2009). In the Slow the Spread Program, 30-yr mean temperature data are interpolated over a digital elevation model and used to predict the dates of male moth flight over the area being monitored (Régnière and Sharov 1998, Régnière and Sharov 1999; Roberts and Ziegler 2007). These predicted dates are used to approximate the timing of trap set and removal. However, because gypsy moth male moth flight can vary because of year-to-year variation in climate, we sought to address behavior and phenology of gypsy moth flight over a geographically diverse landscape to refine current phenological predictions. Classically, this has been accomplished through the use of sentinel traps that are manually and regularly checked, which is a labor-intensive solution.

An alternate approach is to use an automated sampling device. There have been previous reports of the use of automated sampling devices for monitoring insect populations (Hagstrum et al. 1996, Arbogast et al. 2000, Epsky and Shuman 2000, Maghirang et al. 2003), other animal populations (Sabol and Hudson 1995, Bernatas and Nelson 2004), and automated pheromone-baited traps to monitor other Lepidoptera (Schouest and Miller 1994). In this paper, we report on a 5-yr field deployment of automated pheromone-baited traps to monitor the gypsy moth and describe the behavior and phenology of male moth flight.

Materials and Methods

Automated Pheromone-Baited Trap Design. Automated pheromone-baited traps were developed and initially tested by the USDA Animal and Plant Health Inspection Service, Pest Survey Detection and Exclusion Laboratory, OTIS Air National Guard Base, MA. The trap (Fig. 1) is a modified milk carton trap (USDA 2001) containing a piezoelectric counter interfaced with an event data logger (Onset Computer, Bourne, MA). One synthetic pheromone lure was placed in each collection chamber (USDA 2001). On entry
through side slots, a male moth navigates through a tube toward the collection chamber, and when the moth displaces the piezoelectric counter located near the end of the tube, the date and time stamp is recorded by the event data logger. Vapona kill strips (Dichlorvos; 2,2-dichlorovinyl dimethyl phosphate [DDVP]) were placed above the collection chamber (to deter predators) and in the collection chamber (to deter predators and kill male moths; Fig. 1). Each trap also contained a HOBO TidbiT temperature data logger (Onset Computer) to record local temperature conditions.

**Field Deployment.** A total of 30, 81, 81, 80, and 80 automated traps were placed in the field in 2004, 2005, 2006, 2007, and 2008, respectively (Fig. 2). These traps were placed along the leading edge of the current gypsy moth distribution, where expected densities generally range from 50 to 300 moths per trap as ascertained by the placement of traps through the Slow the Spread Program (Decision Support System...
The time stamp associated with events was used to understand the timing of flight behavior. Follow-up analyses were conducted on a subset of traps in which there was a reasonable congruence between moth capture and recorded events, which we defined as those traps in which the ratio of moths-to-events was \( \geq 0.8:1 \) and \( \leq 1.2:1 \) and for which at least 30 moths were trapped. In this subset, we examined the relationship between the latitude at which the trap was deployed and the estimated 5, 50, and 95% dates of recorded events using least squares regression. The relationship between latitude and male moth flight duration, bounded by the estimated dates of 5 and 95% of recorded events, when represented as days and degree-days, was also assessed using least squares regression. All statistical analyses were conducted in R (R Development Core Team 2007).

Results and Discussion

A total of 27 of 30, 49 of 81, 62 of 81, 69 of 80, and 50 of 80 of the automated pheromone-baited traps were recovered with usable data from 2004 to 2008, respectively. Traps without usable data were those that did not catch any moths, were destroyed by wildlife or vandalized, experienced mechanical failure in the event data logger, or were inhabited by other species such as crickets, mice, or spiders that made it impossible to count accurately the number of moths. Also, some traps placed in high-density areas were unusable because the number of male moths was so high that the tube in the trap was completely clogged with moths such that very few moths actually made it into the collection chamber. Thus, given the diameter of the tube (2.75 cm; Fig. 1), this type design would not be appropriate for measuring extremely high density populations (i.e., outbreak populations). Data from all these traps were omitted from our initial analyses.
We used initially a 10-s delay for recording events in the event data logger, but we were also interested in approximating the appropriate delay. We thus examined the distribution of intervals between successive recording events, and in all years, an interval duration of exactly 11 s was greatly over-represented. Among all intervals from 11 to 60 s, when partitioned into 1-s intervals, the interval 11 s accounted for 40.8% of observations, whereas the interval 11–15 s accounted for 63.4% of observations. A distribution of the interval between successive recording events is shown in Fig. 3, which shows less variation in recorded events among interval classes (i.e., 11, 12–15, 16–20, . . ., 56–60 s) at intervals >30 s. This suggests that for these data, a 30-s delay may be more appropriate when recording gypsy moth events. However, because it is difficult to predict the time required for a gypsy moth male, or any other insect, to successively pass through the tube and into the collection chamber, it would be prudent to deploy the traps with a short delay and attempt to deduce a more appropriate delay through exploratory data analysis (Fig. 3) or other methods. For example, future laboratory and field experiments could be developed to measure the required time for moths to navigate through the tube and to determine the effect of male moth density on the expected time between successive moth captures.

Because of the relationship presented in Fig. 3, we used an event recording delay of 30 s when counting the number of recorded events and compared this value with the number of male moths collected in each trap. Although several traps recorded events that were nearly identical to the number of moths in the trap, there was a tendency for overcounting (Fig. 4), even though there was still a strong significantly positive correlation between moths trapped and recorded events ($\rho = 0.77; df = 256; P < 0.0001$). Based on the time stamp of recorded events, peak male moth flight generally occurred between 12 and 17 h (Fig. 5), which is consistent with previous observations (Cardé et al. 1974). There was also a smaller yet consistently

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**Fig. 4.** Relationship between the number of moths and the number of recorded events, 2004–2008. Each symbol represents one trap, and the diagonal line represents the 1:1 relationship.

**Fig. 5.** The number recorded events per trap over time. Note the periodicity in the timing of male moth flight behavior and evidence of crepuscular activity.
observed crepuscular peak between 21 and 22 h (Fig. 5), which has also been previously observed (Odell and Mastro 1980). Giebultowicz et al. (1992) reported that peaks of pheromone titer in females occurs more toward the evening hours with increasing female age, which may provide an explanation for male crepuscular flight activity.

Our subset consisted of 80 automated traps, for which the overall mean ratio of moths to recorded events was 0.98:1, whereas the correlation between trapped moths and recorded events was highly positively significant ($r = 0.99$; df = 79; $P < 0.0001$). Phenological assessments were conducted on this subset, and an example of the phenological distribution for one of the traps is presented in Fig. 6. The gaps in the distribution of recorded events could reflect unfavorable climatic conditions on certain days that may restrict male moth flight. The calendar day of 5, 50, and 95% male flight by latitude is shown in Fig. 7. The slopes for the least squares regression fits to each flight percentile were not significantly different ($F = 0.04$; df = 1.236; $P = 0.95$), and the common slope was 3.8 (SE = 0.05); thus, for each degree of latitude, the calendar day at which 5, 50, or 95% of male flight occurs increases by $\approx 3.8$ d. These results are similar to those reported by Régnière and Sharov (1998), who noted the differences in the timing of male moth flight over elevation and reported an increase of 3.3–4.4 d in observed median male moth flight for each 100 m of elevation.

When considering the total male moth flight period (i.e., the period between the 5th and 95th percentiles of male moth flight), the median of the flight period was 24 d and 228 DD (Fig. 8). There was no significance difference in the duration of male moth flight across latitude, whether days ($F = 0.01$; df = 1.78; $P = 0.94$) or degree-days ($F = 2.08$; df = 1.78; $P = 0.15$) were considered. However, although most traps recorded flight periods <6 wk, 13 of the 80 traps had flight periods $\geq$6 wk, including a maximum of 93 d and 833.5 DD (Fig. 8). Because it is extremely unlikely that local gypsy moth male populations would exhibit flight over such an extended period, it is possible that males, perhaps facilitated through atmospheric transport mechanisms, dispersed into some of these areas after developing under another area’s climatic conditions. Alternatively, the extended male flight period could be because of immature life stages that were anthropogenically introduced, providing that they completed enough development under different climatic conditions to remain asynchronous with the timing of male emergence from resident populations.

Automated sampling devices provide many benefits to IPM programs, which often depend heavily on sampling efforts. Sensors and data loggers that can be incorporated into trapping devices offer an opportunity to greatly enhance our understanding of flight behavior and phenology for a specific insect species and to model these relationships in spatially and temporally explicit detail. Our primary objective in this paper was to present a summary of the utility of automated pheromone-baited traps for monitoring gypsy moth populations, technology that can be transferred to other systems, and to provide an assessment of male moth flight behavior and phenology. Future
studies will examine the phenological aspects of these data in greater detail.

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