FreePSI: an alignment-free approach to estimating exon-inclusion ratios without a reference transcriptome

Supplementary information

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S1 Abundance flow graph

S1.1 Formal definitions of α and PSI

Let α_h denote the relative abundance of isoform h of a gene. For convenience, denote the junction segment formed by exon segments i and j as a pair (i,j), where $i \neq j$. For simplicity, we will also denote an exon segment i as the identity pair (i,i). All such pairs will uniformly be referred to as segments. The indicator variable \mathcal{I}_{hij} is defined as

$$\mathcal{I}_{hij} = \begin{cases} 1 & \text{if isoform } h \text{ covers segment } (i,j) \\ 0 & \text{otherwise} \end{cases}$$

where the segment (i, j) represents an exon segment if i = j or a junction segment otherwise. The parameter α_{ij} for segment (i, j) is formally defined as

$$\alpha_{ij} = \sum_{h} \mathcal{I}_{hij} \alpha_h \tag{S1.1}$$

Note that isoforms will not be explicitly dealt with in our method (*i.e.*, they will be marginalized out), but they are used here to help explain the construction of our model, and will be referred to frequently below.

PSI is defined as the ratio of the total relative abundance of all isoforms containing a given exon over the total relative abundance of all isoforms of the gene containing the exon. Hence, the PSI value of exon segment i can be expressed by the following equation:

$$\psi_i = \frac{\sum_h \mathcal{I}_{hii} \alpha_h}{\sum_h \alpha_h} = \frac{\alpha_{ii}}{\sum_h \alpha_h}$$
 (S1.2)

S1.2 Properties of the abundance flow graph

In order to consider the first and last exon segments of an isoform, we extend the above indicator variables as follows:

$$\mathcal{I}_{hsi} = \begin{cases} 1 & \text{if exon segment } i \text{ is the first exon segment of isoform } h \\ 0 & \text{otherwise} \end{cases}$$

$$\mathcal{I}_{hit} = \begin{cases} 1 & \text{if exon segment } i \text{ is the last exon segment of isoform } h \\ 0 & \text{otherwise} \end{cases}$$

Then, the edge weights α_{si} and α_{it} in an abundance flow graph can be defined formally as

$$\alpha_{si} = \sum_{h} \mathcal{I}_{hsi} \alpha_{h}, \qquad \alpha_{it} = \sum_{h} \mathcal{I}_{hit} \alpha_{h}$$
 (S1.3)

Theorem S1. The following equalities hold:

$$\sum_{i} \alpha_{si} = \sum_{h} \alpha_{h} = \sum_{i} \alpha_{it}$$
 (S1.4)

Proof. Since every isoform has a unique first exon segment, we have the following equality:

$$\sum_{i} \mathcal{I}_{hsi} = 1$$

Hence,

$$\sum_{i} \alpha_{si} = \sum_{i} \sum_{h} \mathcal{I}_{hsi} \alpha_{h}$$
$$= \sum_{h} \alpha_{h} \sum_{i} \mathcal{I}_{hsi}$$
$$= \sum_{h} \alpha_{h}$$

The second equality can be derived similarly.

The abundance flow graph satisfies the flow conservation property, if we consider the edge weights as flow amounts. Figure S1 illustrates an example of this flow conservation property.

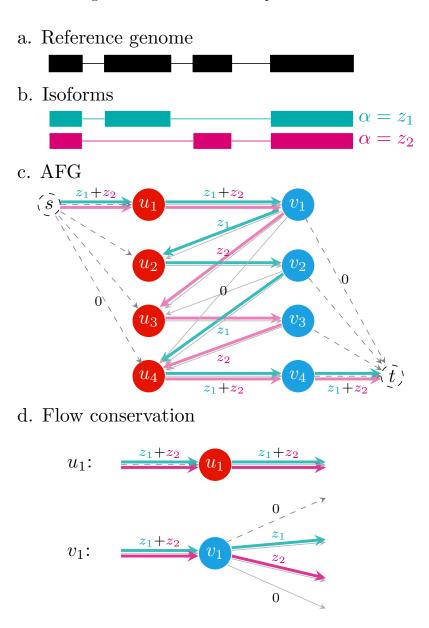


Figure S1: This figure illustrates the flow conservation property of an example AFG for a gene consisting of four exon segments and two isoforms. The exon boundaries are shown in (a) and the relative abundance of the two isoforms $(z_1 \text{ and } z_2)$ are shown in (b). The resulting AFG is shown in (c). The two isoforms are highlighted as two paths with colors cyan and pink from s to t, respectively. Considering the edge weights as flow amounts, the flow conservation property clearly holds for all vertices in U and V. In particular, Figure (d) shows that the flow conservation property holds for vertices u_1 and v_1 .

The following theorem provides a formal derivation of the flow conservation property.

Theorem S2.

$$\alpha_{ii} = \alpha_{si} + \sum_{j < i} \alpha_{ji}, \quad \text{for all } i$$
 (S1.5)

$$\alpha_{ii} = \alpha_{it} + \sum_{j>i} \alpha_{ij}, \quad \text{for all } i$$
 (S1.6)

Proof. We first prove that equality S1.5 holds. For any given isoform, an exon segment i of the isoform is either its first exon segment or next to exon segment j for some j < i. Therefore, for each isoform h,

$$\mathcal{I}_{hii} = \mathcal{I}_{hsi} + \sum_{j < i} \mathcal{I}_{hji} \tag{S1.7}$$

Multiplying both sides of Equation S1.7 by α_h and summing up the equations for all isoforms h, we get

$$\sum_{h} \mathcal{I}_{hii} \alpha_{h} = \sum_{h} \left(\mathcal{I}_{hsi} + \sum_{j < i} \mathcal{I}_{hji} \right) \alpha_{h}$$

$$\Rightarrow \sum_{h} \mathcal{I}_{hii} \alpha_{h} = \sum_{h} \mathcal{I}_{hsi} \alpha_{h} + \sum_{j < i} \sum_{h} \mathcal{I}_{hji} \alpha_{h}$$

$$\Rightarrow \alpha_{ii} = \alpha_{si} + \sum_{j < i} \alpha_{ji} \qquad \text{(by Equations S1.1 and S1.3)}$$

Hence, equality S1.5 holds. Equality S1.6 can be proven similarly.

Corollary S1. The PSI values can be rewritten as

$$\psi_i = \frac{\alpha_{ii}}{\sum_i \alpha_{ii} - \sum_i \sum_{j>i} \alpha_{ij}}$$
 (S1.8)

Proof. By Equation S1.2, we only need to focus on the denominator.

$$\sum_{h} \alpha_{h} = \sum_{i} \alpha_{si}$$
 (by Equation S1.4)
$$= \sum_{i} \left(\alpha_{ii} - \sum_{j < i} \alpha_{ji} \right)$$
 (by Equation S1.5)
$$= \sum_{i} \alpha_{ii} - \sum_{i} \sum_{j < i} \alpha_{ji}$$

$$= \sum_{i} \alpha_{ii} - \sum_{i} \sum_{j > i} \alpha_{ij}$$

Since $\alpha_{si} \geq 0$ and $\alpha_{it} \geq 0$ for all i, we have the following constraints for the parameters α_{ij} :

Corollary S2.

$$\alpha_{ii} \geq \sum_{j < i} \alpha_{ji}, \quad for \ all \ i$$
 (S1.9)

$$\alpha_{ii} \geq \sum_{j>i} \alpha_{ij}, \quad for \ all \ i$$
 (S1.10)

These constraints are crucial for an accurate estimation of our probabilistic model.

S2 Probabilistic generative model

S2.1 Subscript rearrangement

In order to perform a genome-wide analysis, we use a single index s to indicate a segment (exon or junction) of any gene g, and α_{gs} to denote the total relative abundance of all isoforms containing segment s of gene g. Hence, the PSI value of exon segment i of gene g can be rewritten as

$$\psi_{gi} = \frac{\alpha_{gi}}{\sum_{s \in g} \alpha_{gs} - \sum_{s \in g} \alpha_{gs}}$$
(S2.1)
s is an exon segment s is a junction segment

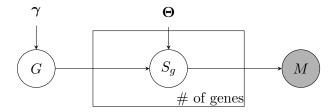
S2.2 Random variables and parameters

Three random variables are defined for the probabilistic generative model.

- 1. G represents a random gene. Thus, $P(G = g) = \gamma_g$ indicates that the probability that a read is generated from gene g is γ_g .
- 2. S_g represents a random segment of gene g, and $P(S_g = s | G = g) = \theta_{gs}$ indicates that each read from gene g is generated from segment s with conditional probability θ_{gs} .
- 3. M represents a random k-mer, and P(M=m) indicates the probability of k-mer m being observed.

S2.3 Graphical model

The probabilistic generative model can be represented by the following graphical model:



The probability of observing a k-mer m can be calculated as

$$\begin{split} & \text{P} \left(M = m \right) \\ & = \sum_{g} \sum_{s \in g} \text{P} \left(M = m, S_g = s, G = g \right) \\ & = \sum_{g} \sum_{s \in g} \text{P} \left(M = m | S_g = s, G = g \right) \text{P} \left(S_g = s | G = g \right) \text{P} \left(G = g \right) \\ & = \sum_{g} \text{P} \left(G = g \right) \sum_{s \in g} \text{P} \left(S_g = s | G = g \right) \text{P} \left(M = m | S_g = s, G = g \right) \\ & = \sum_{g} \gamma_g \sum_{s \in g} \theta_{gs} \text{P} \left(M = m | S_g = s, G = g \right) \end{split}$$

where $P(M = m | S_g = s, G = g)$ denotes the theoretical distribution of k-mers on segment s.

S2.4 Relationship between γ , θ and α

Let L_{gs} denote the length of segment s of gene g and L_{gh} denote the length of isoform h of gene g. The number of possible starting sites for a read in the segment or isoform are

$$\widetilde{L}_{gs} = L_{gs} - L_{\text{read}} + 1$$
 $\widetilde{L}_{gh} = L_{gh} - L_{\text{read}} + 1$

respectively, where L_{read} denotes the read length. If the relative abundance is measured by TPM, α_{gh} can be calculated as

$$\alpha_{gh} = \frac{\frac{f_{gh}}{\tilde{L}_{gh}}}{\sum_{g} \sum_{h' \in q} \frac{f_{gh'}}{\tilde{L}_{gh'}} \times 10^{-6}}$$
 (S2.2)

where f_{gh} represents the number of reads from isoform h of gene g. Similarly, let f_{gs} denote the number of reads from segment s of gene g, and the indicator variable \mathcal{I}_{ghs} to indicate whether isoform h contains segment s of gene g. Assuming that the reads are uniformly distributed in each segment/isoform, we get

$$f_{gs} = \sum_{h \in q} \mathcal{I}_{ghs} f_{gh} \frac{\widetilde{L}_{gs}}{\widetilde{L}_{gh}}$$
 (S2.3)

Note that the reads are generated by an implicit two-level process in the above probabilistic model: from genes to isoforms and then to segments. Equation S2.3 marginalizes out isoforms to associate the reads with segments directly.

Since the reads are assumed to be generated from the probabilistic model, we have

$$\gamma_g \theta_{gs} \approx \frac{f_{gs}}{\sum_g \sum_{h \in g} f_{gh}}$$
(S2.4)

The following proposition shows a relationship among γ , θ and α .

Proposition S1.

$$\alpha_{gs} \approx \frac{Z_2}{Z_1} \frac{\gamma_g \theta_{gs}}{\tilde{L}_{gs}} \tag{S2.5}$$

where $Z_1 = \sum_g \sum_{h \in g} \frac{f_{gh}}{\tilde{L}_{gh}} \times 10^{-6}$ and $Z_2 = \sum_g \sum_{h \in g} f_{gh}$.

Proof.

$$\gamma_g \theta_{gs} \approx \frac{f_{gs}}{Z_2} \qquad \text{(by Equation S2.4)}$$

$$= \frac{1}{Z_2} \sum_{h \in g} \mathcal{I}_{ghs} f_{gh} \frac{\widetilde{L}_{gs}}{\widetilde{L}_{gh}} \qquad \text{(by Equation S2.3)}$$

$$= \frac{\widetilde{L}_{gs}}{Z_2} \sum_{h \in g} \mathcal{I}_{ghs} \frac{f_{gh}}{\widetilde{L}_{gh}}$$

$$= \frac{\widetilde{L}_{gs}}{Z_2} \sum_{h \in g} \mathcal{I}_{ghs} \alpha_{gh} Z_1 \qquad \text{(by Equation S2.2)}$$

$$= \frac{Z_1}{Z_2} \widetilde{L}_{gs} \sum_{h \in g} \mathcal{I}_{ghs} \alpha_{gh}$$

$$= \frac{Z_1}{Z_2} \widetilde{L}_{gs} \alpha_{gs} \qquad \text{(by Equation S1.1)}$$

Therefore, the definition of PSI given in Equation S2.1 can be rewritten in terms of θ as follows:

$$\psi_{gi} \approx \frac{\frac{\theta_{gi}}{\widetilde{L}_{gi}}}{\sum_{s \in g} \frac{\theta_{gs}}{\widetilde{L}_{gs}} - \sum_{s \in g} \frac{\theta_{gs}}{\widetilde{L}_{gs}}}$$
(S2.6)

The linear inequalities S1.9 and S1.10 can also be transformed into the constraints on θ . For gene g, the parameter θ should satisfy $A_g\theta_g \geq 0$, which is the matrix-form of the constraints. More specifically, A_g is composed of three parts:

$$\boldsymbol{A}_{g} = \begin{pmatrix} \boldsymbol{D}_{g} \\ \boldsymbol{U}_{g} \\ \boldsymbol{B}_{g} \end{pmatrix} \tag{S2.7}$$

Each row of $D_g \in \mathbb{R}^{N_e(g) \times N_s(g)}$ denotes the coefficients of the linear constraints between each exon segment and its downstream junction segments (*i.e.*, the inequality in Equation S1.10). $N_e(g)$ denotes the number of exon segments in gene g and $N_s(g)$ the number of (exon and junction) segments in gene g. The element at row i and column s is defined as

$$D_{g}(i,s) = \begin{cases} \frac{1}{\widetilde{L}_{gs}} & \text{if } s \text{ is an exon segment } i \\ -\frac{1}{\widetilde{L}_{gs}} & \text{if } s \text{ is a junction segment beginning at exon segment } i \\ 0 & \text{otherwise} \end{cases}$$
 (S2.8)

Similarly, each row of $U_g \in \mathbb{R}^{N_e(g) \times N_s(g)}$ denotes the coefficients of the linear constraints between each exon segment and its upstream junction segments (*i.e.*, the inequality in Equation S1.9). Its elements are defined as

$$U_{g}(i,s) = \begin{cases} \frac{1}{\widetilde{L}_{gs}} & \text{if } s \text{ is exon segment } i \\ -\frac{1}{\widetilde{L}_{gs}} & \text{if } s \text{ is a junction segment ending at exon segment } i \\ 0 & \text{otherwise} \end{cases}$$
(S2.9)

 $B_g \in \mathbb{R}^{(N_s(g)-N_e(g))\times N_s(g)}$ represents the non-negativity constraints on the relative abundance of junction segments, which is defined as

where
$$\mathbf{B}_{g} = (\mathbf{0}, \mathbf{I})$$

$$\mathbf{0} \in \mathbb{R}^{(N_{s}(g) - N_{e}(g)) \times N_{e}(g)}$$

$$\mathbf{I} \in \mathbb{R}^{(N_{s}(g) - N_{e}(g)) \times (N_{s}(g) - N_{e}(g))}$$

$$(S2.10)$$

The non-negativity constraints on the relative abundance of exon segments are omitted here since they are already implied by the constraints in D_g, U_g and B_g .

S2.5 Theoretical distribution of k-mers

Let r represent a read and m_r represent a k-mer in r. Define the following indicator function:

$$\mathcal{I}(m, m_r) = \begin{cases} 1 & \text{if } m = m_r \\ 0 & \text{if } m \neq m_r \end{cases}$$

Recall $c_{gsm} = P(M = m | S_g = s, G = g)$ denotes the theoretical distribution of k-mers on segment s of gene g, under the assumption that the reads are uniformly distributed on each segment. The following proposition is easy to prove.

Proposition S2.

$$c_{gsm} := P(M = m | S_g = s, G = g) = \frac{\mathcal{F}_{gsm}}{\widetilde{L}_{gs} (L_{read} - K + 1)}$$
 (S2.11)

where

$$\mathcal{F}_{gsm} = \sum_{r \in s} \sum_{m_r} \mathcal{I}(m_r, m)$$
 (S2.12)

Finally, the probability of observing a k-mer m is

$$P(M = m) = \sum_{g} \gamma_g \sum_{s \in g} \theta_{gs} c_{gsm}$$
 (S2.13)

where γ_g and θ_{gs} are model parameters to be estimated.

S3 Algorithms

S3.1 Maximum likelihood estimation

Let n_m denote the number of occurrences of k-mer m in the input RNA-seq reads. The likelihood of observing all k-mers in the input is

$$\mathcal{L}(\gamma, \mathbf{\Theta}) = \prod_{m} P(M = m)^{n_m}$$

$$\log \mathcal{L}(\gamma, \mathbf{\Theta}) = \sum_{m} n_m \log P(M = m)$$

$$= \sum_{m} n_m \log \left(\sum_{g} \gamma_g \sum_{s \in g} \theta_{gs} c_{gsm} \right)$$

The maximum likelihood estimation is to solve the following nonlinear constrained optimization:

$$\begin{array}{ll} \max & \log \mathcal{L}\left(\boldsymbol{\gamma},\boldsymbol{\Theta}\right) \\ \text{s.t.} & \boldsymbol{A}_g\boldsymbol{\theta}_g \geq 0, \quad \text{for all gene } g \\ & \sum_{s \in g} \theta_{gs} = 1, \quad \text{for all gene } g \\ & \sum_{g} \gamma_g = 1, \quad \forall \gamma_g \geq 0, \quad \forall \theta_{gs} \geq 0 \end{array}$$

S3.2 The expectation-maximization algorithm

An initial feasible solution is obtained via the following algorithm.

```
Algorithm S1: Initial feasible solution construction
      Input: c_{gsm}, n_m and A_g (for all g, s and m)
      Output: \theta^{(0)} and \gamma^{(0)}
            Z_m \leftarrow \sum_g \sum_{s \in g} c_{gsm}, \quad \theta_{gs} \leftarrow \sum_m n_m \frac{c_{gsm}}{Z_m}, \quad \gamma_g \leftarrow \sum_{s \in g} \theta_{gs} \qquad \qquad \triangleright \text{ distribute } n_m \text{ to segments}
Y \leftarrow \sum_g \gamma_g, \quad \gamma_g \leftarrow \frac{\gamma_g}{Y} \qquad \qquad \triangleright \text{ normalize } \gamma
             forall g do
 4
                    forall row vector a_r in A_g with a_r\theta_g < 0 do
 5
                           if \theta_{gs} = 0 for some exon segment s then
 6
                                 set all \theta_{gs'} \leftarrow 0 for all adjacent junction segments s'
                                                                                                                                                             {\,\vartriangleright\,}make \theta feasible
  7
                          while a_r \theta_g < 0 do \theta_{gs} \leftarrow \theta_{gs} \times 10 for all exon segments s end
  8
 9
                                                                                                                                                             \triangleright make \theta feasible
10
11
                   X_g \leftarrow \sum_{s \in q} \theta_{gs}, \quad \theta_{gs} \leftarrow \frac{\theta_{gs}}{X_g}
                                                                                                                                                                     \triangleright normalize \theta
13
             end
14
             return \boldsymbol{\theta}^{(0)} and \boldsymbol{\gamma}^{(0)}
15
16 end
```

In the E-step of the EM algorithm, we derive the expected log-likelihood using the current

estimation of $\gamma_g^{(t)}$ and $\theta_{gs}^{(t)}$ as follows:

$$Q(\gamma, \mathbf{\Theta}) = \sum_{m} n_{m} \sum_{g} \mu_{gm}^{(t)} \log \left(\gamma_{g} \sum_{s \in g} c_{gsm} \theta_{gs} \right)$$
 (S3.1)

where

$$\mu_{gm}^{(t)} = \frac{\gamma_g^{(t)} \sum\limits_{s \in g} \theta_{gs}^{(t)} c_{gsm}}{\sum\limits_{g} \gamma_g^{(t)} \sum\limits_{s \in g} \theta_{gs}^{(t)} c_{gsm}}$$

By expanding the product in the logarithmic term of Equation S3.1, $\mathcal{Q}(\gamma, \Theta)$ can be decomposed as the summation of two independent parts:

$$Q(\gamma, \mathbf{\Theta}) = Q^{\mathrm{I}}(\gamma) + \sum_{q} Q_{g}^{\mathrm{II}}(\boldsymbol{\theta}_{g})$$
 (S3.2)

where

$$\begin{aligned} \mathcal{Q}^{\mathrm{I}}\left(\boldsymbol{\gamma}\right) &=& \sum_{m} \sum_{g} \mu_{gm}^{(t)} \log \left(\gamma_{g}\right) \\ \\ \mathcal{Q}_{g}^{\mathrm{II}}\left(\boldsymbol{\theta}_{g}\right) &=& \sum_{m} \mu_{gm}^{(t)} \log \left(\sum_{s \in g} \theta_{gs} c_{gsm}\right) \end{aligned}$$

The M-step of the algorithm is to maximize the expectation of the log-likelihood given in Equation S3.2. This is divided into two independent parts. The first part is to solve

$$\max_{\text{s.t.}} \quad \mathcal{Q}^{\text{I}}(\gamma)$$
s.t.
$$\sum_{g} \gamma_g = 1, \quad \forall \gamma_g \ge 0$$

By using the Lagrangian multiplier method, a closed-form solution for this part can be derived:

$$\gamma_g^{(t+1)} = \frac{\sum\limits_{m} \mu_{gm}^{(t)}}{\sum\limits_{m} \sum\limits_{q} \mu_{gm}^{(t)}}$$

The second part consists of a similar optimization problem for each gene g:

$$\max \qquad \mathcal{Q}_g^{\mathrm{II}}(\boldsymbol{\theta}_g)$$
s.t. $\boldsymbol{A}_g \boldsymbol{\theta}_g \ge 0, \quad \sum_{s \in g} \theta_{gs} = 1, \quad \forall \theta_{gs} \ge 0$ (S3.3)

Since a closed-form solution for this problem is unavailable due to the linear inequality constraints, the conjugate gradient projection descent (CGPD) algorithm is applied to solve the problem for all genes concurrently.

S3.3 The conjugate gradient projection descent algorithm

The CGPD algorithm is an extension of the well-known gradient projection descent (GPD) algorithm [1]. For completeness, a pseudocode of the CGPD algorithm is given below.

```
Algorithm S2: The CGPD algorithm
```

```
\overline{\textbf{Input: } \boldsymbol{\theta}_g, \, \boldsymbol{A}_g}
        Output: \arg \max \mathcal{Q}_g^{\text{II}}(\boldsymbol{\theta}_g) \text{ s.t. } \boldsymbol{A}_g \boldsymbol{\theta}_g \geq 0, \ \sum_{s \in g} \theta_{gs} = 1, \ \forall \theta_{gs} \geq 0
               i \leftarrow 0, \boldsymbol{x}^{(i)} \leftarrow \boldsymbol{\theta}_g, \boldsymbol{g}^{(i)} \leftarrow \nabla \mathcal{Q}_q^{\text{II}} \left( \boldsymbol{x}^{(i)} \right)
                q \leftarrow 1, \mathbf{N}_q \leftarrow (1, 1, \cdots, 1)^{\top}
  3
                forall row vector a_j in A_g do
  4
                        if a_j x^{(i)} = 0 then
   5
                              oldsymbol{N}_{q+1} \leftarrow \left(oldsymbol{N}_q, oldsymbol{a}_j^	op
ight) \ q \leftarrow q+1
  6
  7
  8
                          end
                 \mathbf{end}
  9
                \boldsymbol{H}_q^{(i)} \leftarrow \boldsymbol{I}^{q \times q}
10
11
                          oldsymbol{s}^{(i)} = oldsymbol{H}_q^{(i)} oldsymbol{g}^{(i)}
                                                                                                                                              ▷ construct conjugate gradient direction
12
                        oldsymbol{lpha} \leftarrow ig(oldsymbol{N}_q^	op oldsymbol{N}_q^ig)^{-1} oldsymbol{N}_q^	op oldsymbol{g}^{(i)} \ b_{jj} \leftarrow ig(oldsymbol{N}_q^	op oldsymbol{N}_qig)_{jj}^{-1}
                                                                                                                                              ▷ construct projected gradient direction
13
14
                         if s^{(i)} = 0 and \forall \alpha_j \leq 0 then
15
                            | return x^{(i)}
16
                          else if \|s^{(i)}\| \le \max\left\{\frac{1}{2}\alpha_j b_{jj}^{-1/2}\right\} then
17
                                 update N_q as N_{q-1}

update H_q^{(i)} as H_{q-1}^{(i)}

q \leftarrow q - 1
                                                                                                                                                                                  \triangleright deactivate a constraint
18
19
20
21
                                  \lambda^{(i)} \leftarrow \arg \max \mathcal{Q}_g^{\mathrm{II}} \left( \boldsymbol{x}^{(i)} + \lambda \boldsymbol{s}^{(i)} \right) \quad \text{s.t. } 0 \leq \lambda \leq \lambda_{\text{bound}}
                                                                                                                                                                                ⊳ perform line search
22
                                  if \lambda^{(i)} = 0 then
23
                                     return x^{(i)}
24
                                  else if \lambda^{(i)} = \lambda_{bound} then
update N_q as N_{q+1}
update H_q^{(i)} as H_{q+1}^{(i+1)}
q \leftarrow q + 1
25

    ▷ activate a constraint

26
27
28
29
                                          update \boldsymbol{H}_q^{(i)} as \boldsymbol{H}_q^{(i+1)}
                                                                                                                                                                                        ▶ keep the constraints
30
31
                                  oldsymbol{x}^{(i+1)} \leftarrow oldsymbol{x}^{(i)} + \lambda^{(i)} oldsymbol{s}^{(i)} \;, \, oldsymbol{g}^{(i+1)} \leftarrow 
abla \mathcal{Q}_q^{	ext{II}} \left(oldsymbol{x}^{(i+1)}
ight)
32
                                  i \leftarrow i+1
33
                          end
34
                 end
35
36 end
```

S4 Some implementation details

S4.1 Linear indexing algorithm

```
Algorithm S3: Linear indexing algorithm
    Input: sequence S with length L
    Output: indices of all k-mers in S
 1 begin
 \mathbf{2}
        a \leftarrow 0
        for i = 1, \dots, K - 1 do
 3
            a \leftarrow (a \text{ lsh } 2) \text{ or } H(S_i)
 4
 \mathbf{5}
        end
 6
        mask \leftarrow (1 \text{ lsh } K) - 1
        A \leftarrow \{\}
 7
        for i = K, \dots, L do
 8
            a \leftarrow (a \text{ lsh } 2) \text{ or } H(S_i)
 9
            a \leftarrow a \text{ and } mask
10
            A \leftarrow A \cup \{a\}
11
        end
12
13
        return A
14 end
    Input: base pair s
    Output: index of s
15 function H
        switch s do
16
            case 'A' do return 0
            case 'C' do return 1
18
            case 'G' do return 2
19
            case 'T' do return 3
20
        end
21
22 end
```

S4.2 Techniques for improving the efficiency of CGPD

S4.2.1 Offline computation for part of $\nabla Q_q^{\text{II}}(\theta_q)$

 $\nabla \mathcal{Q}_{q}^{\mathrm{II}}\left(\boldsymbol{\theta}_{g}\right)$ can be represented by

$$\nabla \mathcal{Q}_g^{\text{II}}(\boldsymbol{\theta}_g) = \text{diag}^{-1} \left(\boldsymbol{C}_g \boldsymbol{C}_g^{\top} \boldsymbol{\theta}_g \right) (\boldsymbol{C}_g \boldsymbol{\mu}_g)$$
 (S4.1)

where $C_g \in \mathbb{R}^{n_s(g) \times n_k}$ is the matrix form of c_{gsm} and $\boldsymbol{\mu}_g \in \mathbb{R}^{n_k \times 1}$ is the vector form of μ_{gm} , with n_k denoting the number of k-mers and $n_s(g)$ the number of segments in gene g. Assuming that the CGPD algorithm converges in T iterations, its time complexity is then $O\left(Tn_kn_s(g)^2\right)$, if $\nabla \mathcal{Q}_g^{\text{II}}\left(\boldsymbol{\theta}_g\right)$ is computed directly according to Equation S4.1. Since only $\boldsymbol{\theta}_g$ is changed during the iterations, $C_g \boldsymbol{C}_g^{\top}$ and $C_g \boldsymbol{\mu}_g$ (the iteration-invariant parts) can be computed in advance. This way, the time complexity is reduced into $O\left(n_k n_s(g)^2 + Tn_s(g)^2\right)$.

S4.2.2 Replacing outer product of vectors

The CGPD algorithm performs many vector outer product operation in the following form:

$$oldsymbol{H}^{(t+1)} = oldsymbol{H}^{(t)} \pm oldsymbol{q} oldsymbol{q}^{ op}$$

where $\boldsymbol{H} \in \mathbb{R}^{n \times n}$ and $\boldsymbol{q} \in \mathbb{R}^{n \times 1}$. A direct computation requires allocating $n \times n$ new memory to store the matrix $\boldsymbol{q}\boldsymbol{q}^{\top}$, which is redundant and becomes an efficiency bottleneck of FreePSI. To speed up this frequent operation, we update \boldsymbol{H} by in-space column-wise operations as follows:

$$\boldsymbol{H}_{\cdot i}^{(t+1)} \leftarrow \boldsymbol{H}_{\cdot i}^{(t)} \pm q_i \boldsymbol{q}$$
 for $i = 1, \dots, n$

which does not require temporary memory allocation.

S5 Supplementary results and discussion

S5.1 Simulated data evaluation

Genome-wide correlation on simulated data

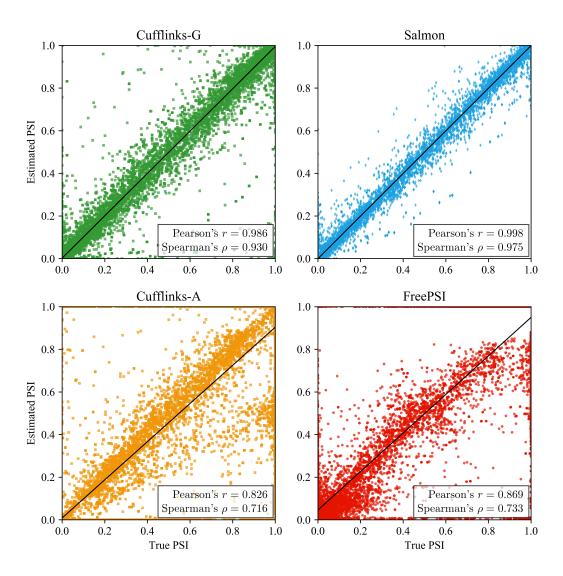


Figure S2: The scatter plot for genome-wide evaluation of different methods on the simulated data. The X-axis shows the true PSI values in the simulation and the Y-axis the PSI values estimated by different methods.

Exon-centric correlation on simulated data

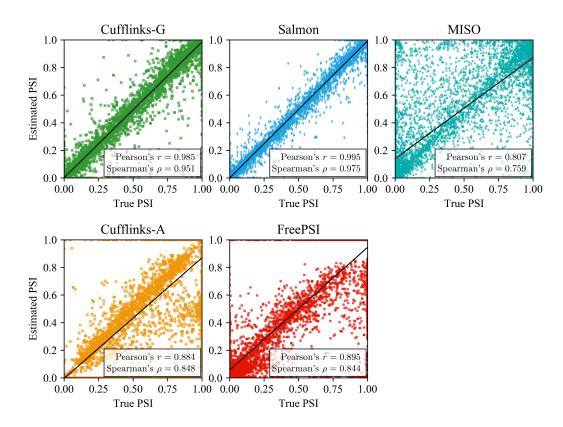


Figure S3: The scatter plot for exon-centric evaluation of different methods on the simulated data. The X-axis shows the true PSI values in the simulation and the Y-axis the PSI values estimated by different methods.

S5.2 Real data evaluation

Exon-centric correlation on real data

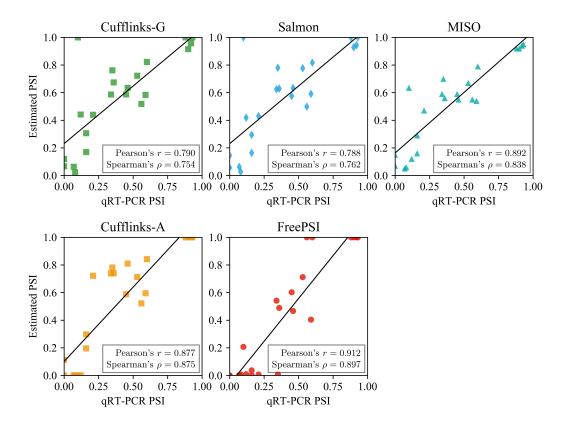


Figure S4: The scatter plot for exon-centric evaluation of different methods on the real data. The X-axis shows the true PSI values calculated from the qRT-PCR PSI results and the Y-axis the PSI values estimated by different methods.

S5.3 Impact of the quality of transcriptome assembly

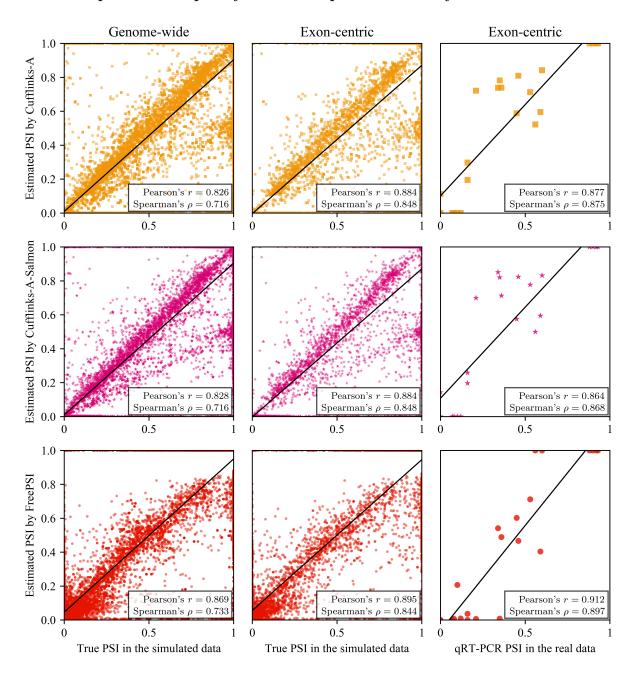


Figure S5: The scatter plots for Cufflinks-A (row 1), Cufflinks-A-Salmon (row 2) and FreePSI (row 3). Note that the plots for Cufflinks-A and FreePSI also appear in Figure 3 and Supplementary Figures S2, S3 and S4. We include them here again for the reader's convenience.

S5.4 Impact of k-mer length on FreePSI

The parameter K representing the length k-mers considered in FreePSI is critical to the performance of FreePSI. We use the simulated dataset with 100 million reads to study the impact of K.

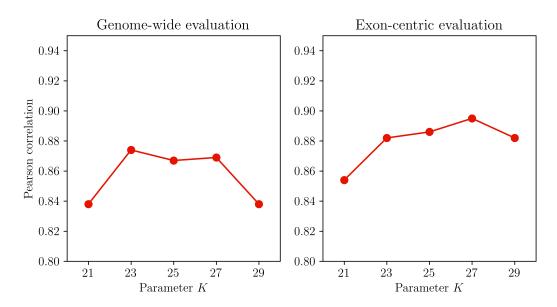


Figure S6: The performance of FreePSI under several choices of K.

The above figure shows the performance of FreePSI on the simulated dataset when different values of K was applied. In both evaluations, the performance peaked under a moderate K, although the optimal K values were different. The reason is that a smaller K induces more kmers shared by different segments, which increases the difficulty of the estimation. On the other hand, a larger K results in fewer k-mers representing a segment, which makes the estimation more sensitive to sequencing errors. Hence, a moderate K in the range of 23 and 27 seems to work well for FreePSI generally, and we set the default K as 27.

S5.5 Supplementary tables

Table S1: Impact of sequencing depth on the performance of MISO, Salmon, Cufflinks-A, and FreePSI on simulated data. The numbers of genes and exons selected for the genome-wide and exon-centric evaluations, respectively, are also shown in the table.

	# reads	20M	50M	100M
	# genes	6907	7025	7032
Pearson correlation	Salmon	0.997	0.998	0.998
for genome-wide evaluation	Cufflinks-A	0.783	0.836	0.826
	FreePSI	0.783	0.837	0.869
	# exons	10930	10958	10919
Pearson correlation	MISO	0.678	0.750	0.807
	Salmon	0.978	0.994	0.995
for exon-centric evaluation	Cufflinks-A	0.773	0.845	0.884
	FreePSI	0.817	0.862	0.895

Table S2: Performance of Salmon and Cufflinks-G on incomplete reference transcriptomes with different sampling rates. Here, a sampling rate represents what percentage of the true reference transcriptome would be covered in the provided reference transcriptome.

	Sampling rate	100%	90%	80%	70%
Pearson correlation	Salmon	0.998	0.913	0.804	0.725
for genome-wide evaluation	Cufflinks-G	0.986	0.904	0.796	0.718
Pearson correlation	Salmon	0.995	0.934	0.848	0.780
for exon-centric evaluation	Cufflinks-G	0.985	0.926	0.843	0.777

Table S3: Performance of Salmon, Cufflinks-G, Cufflinks-A, and FreePSI on genes under different TPM thresholds.

TPM	0	1	2	5	10
Salmon	0.967	0.997	0.997	0.998	0.998
Cufflinks-G	0.964	0.982	0.983	0.985	0.986
Cufflinks-A	0.742	0.684	0.751	0.812	0.826
FreePSI	0.856	0.802	0.828	0.856	0.869

Table S4: Performance of Salmon, Cufflink-G, Cufflinks-A, and FreePSI on 14 gene families with large proportions of multi-mapped reads in the simulation. As a comparison, the corresponding numbers for the whole genome are given in the last row of the table.

Gene family	Multi-read proportion	FreePSI	Cufflinks-A	Salmon	Cufflinks-G	# genes	# isoforms	# expressed genes
PAR1	38.16 %	0.968	0.230	1.000	0.434	21	103	8
GST	36.61 %	0.760	0.419	1.000	1.000	23	57	8
CDK	27.12 %	0.911	0.615	0.999	0.980	26	88	13
MAGE	25.64 %	0.978	0.541	0.999	0.997	39	103	7
NLR	15.90 %	0.805	0.524	1.000	0.998	23	60	9
TTC	13.37 %	0.709	0.698	0.999	0.984	115	373	46
TUB	10.78~%	0.907	0.755	0.999	0.998	24	59	11
SDR	9.95~%	0.907	0.825	1.000	0.999	75	179	23
NUP	7.88 %	0.536	0.884	1.000	0.994	32	89	15
DDX	5.63 %	0.943	0.867	0.994	0.974	42	108	17
CLEC	5.34 %	0.950	0.891	0.998	0.993	46	130	21
TRIM	5.23~%	0.931	0.849	1.000	0.997	80	189	26
SCAR	4.49~%	0.915	0.942	0.999	0.996	27	79	9
AKAP	3.04~%	0.947	0.849	1.000	0.882	29	73	10
Whole genome	2.48 %	0.869	0.826	0.998	0.986	23983	57822	7032

S6 Software configurations

- Jellyfish on simulated data jellyfish count -m 27 -s 100M -t 16 -Q 5 \${READS} -o \${OUTPUT}
- Jellyfish on real data jellyfish count -m 27 -s 100M -t 16 -Q A -L 10 \${READS} -o \${OUTPUT}
- HISAT

```
hisat2 --fr --dta-cufflinks -p 16 -x ${GENOME_INDEX} -1 ${READS-1} -2 ${READS-2} | samtools view --threads 16 -Sbo ${BAM_FILE}
```

• FreePSI

```
freePSI build -k 27 -p 16 -g ${REF_GENOME} -1 ${READS-1} -2 ${READS-2}
-a ${EXON_BND} -o ${HASHTABLE}
freePSI quant -k 27 -p 16 -i ${HASHTABLE} -o ${OUTPUT}
```

• Salmon

```
salmon index -t ${REF_TRANSCRIPTOME} -i ${INDEX}
salmon quant -p 16 -l ISF -i ${INDEX} -1 ${READS-1} -2 ${READS-2} -o ${OUTPUT}
```

• Cufflinks-A

```
cufflinks -u -b GENOME_INDEX -p 16 --library-type fr-secondstrand GENOME_INDEX -o GENOME_INDEX
```

• Cufflinks-G

```
cufflinks -u -b ${GENOME_INDEX} -p 16 --library-type fr-secondstrand ${BAM}
-G ${REF_TRANSCRIPTOME} -o ${OUTPUT}
```

• MISO

```
miso --run ${REF_SPLICING} ${BAM_FILE} --settings-filename=${DEFAULT_MISO_SETTING}
-p 16 --read-len ${READ_LEN} output-dir ${OUTPUT}
```

• Flux Simulator (.par file)

REF_FILE_NAME \${REF_TRANSCRIPTOME}

GEN_DIR \${REF_GENOME}

NB_MOLECULES 5000000

TSS_MEAN 25

POLYA_SCALE NaN

POLYA_SHAPE NaN

RTRANSCRIPTION YES

RT_PRIMER RH

FRAG_SUBSTRATE RNA

FRAG_METHOD UR

FRAG_UR_ETA NaN

FRAG_UR_DO 1

READ_NUMBER 10000000

READ_LENGTH 76

PAIRED_END YES

ERR_FILE 76

FASTA YES

UNIQUE_IDS YES

More details can be found in the source code.

References

[1] Jo Bo Rosen. The gradient projection method for nonlinear programming, part i. linear constraints. *Journal of the Society for Industrial and Applied Mathematics*, 8(1):181–217, 1960.